

COMPUTER ANALYSIS OF INDETERMINATE FRAMES LOADED NORMAL TO THEIR PLANE USING THE METHOD OF VIRTUAL WORK

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INTRODUCTION

The author has previously presented a computer program to solve indeterminate frames loaded in their planes using the well known method of "VIRTUAL WORK". The method can be used to all types of loads, settlements of supports, temperature changes, and several cases of loadings, acting simultaneously. [1]. This paper gives the solution when loads are normal to the plane of the structure. It is assumed that this paper uses all principles, and sign conventions presented before, which will be briefly given later.

ASSUMPTIONS

The assumptions adopted here will be.

1. The members of the frame are considered each as two members when using the previous program "VW".

The first of these members, with two various end moments will resist the developing moments in the frame and the second with two equal twisting moments to resist the internal torsional moments in the frame.

2. The elastic lengths for these two members will be:
 - a. For first members resisting the bending moments $L1(I) = (L/EI) (I)$
 - b. For second members resisting the torsional moments $TL1(I) = (L/EI)*T1(I)$

where

$$T1 = (EI/GJ)$$

i.e.

$$TL1 = L1*T1$$

Hence, in the computer program "VWN" presented in this paper, $n = 4 \times \text{no. Of members in the frame.}$

MORE ABOUT SIGN CONVENTION

In addition to program "VW"⁽¹⁾, notice that:

1. The bending moments developing in the member will act in a plane normal to that of the frame.

Notice that all moments acting above the plane of the frame will be positive.

If we rotate these bending moment diagrams to become drawn in the plane of the frame on the left of the vertical members and on top of all other members, horizontal or inclined, they will become negative moments.

These moments are produced by moment vectors normal to the axis of the member. Moment vectors acting on the right end of the member, (looking from inside) produce moments on the other side of the member, i.e, negative moments.

On the other hand, the torsion in the members is produced from moment vector along the axis of the member. If these vectors appear as if giving tension in the member, the resulting torsion will be positive. More details will be shown in the following examples.

RESOLUTION OF MOMENT VECTORS

Figure (1) shows member CD, with resultant action at end D consisting of moment vector V, making an angle ϕ w.r.t the member, together with a concentrated force P normal to the plane downwards. The resolution of V gives:

a- Moment vector, normal to CD; $M = V \sin \phi$

b- Torsion vector, along CD; $T = V \cos \phi$

Now M is to the right of CD, hence the rotated B.M. Diagram appears on the other side of the member, i.e.; negative moment.

Due to the presence of P, normal to the plane, (downwards) the bending moment at the far end to the left, will be:

$$M1 = M + P * L$$

Step of Solution

The vector T, giving torsion, appears axial to the member, producing axial tensile force, hence gives positive torsion.

Figure (2) shows a member EF to the right where $M = V \sin \phi$, and $T = -V \cos \phi$

The B.M. at E will be; $M = V \sin \phi$, and at the far end $M1 = M + P * L$, all negative. The application of the method is clarified by following examples.

The main programs are first copied onto the diskettes used in the solution. These programs are:

1. Appendix (1) : "VWNM"
2. Appendix (2) : "DATVWNM"

Next

1. Load the data VWNM program .
[write F1 "DATVWNM"]
2. Fill in the necessary data in the diagram.
3. Save the diagram as : F4/ DATVWN4M; 4 being any chosen number.
4. Add [MERGE "VWNM"]
when (OK), run the program as (F2); to get the final requirement which asks whether you need the moments and torsion produced on the screen (1), or printer (2), or not (3). chose (1), then (2), then (3).

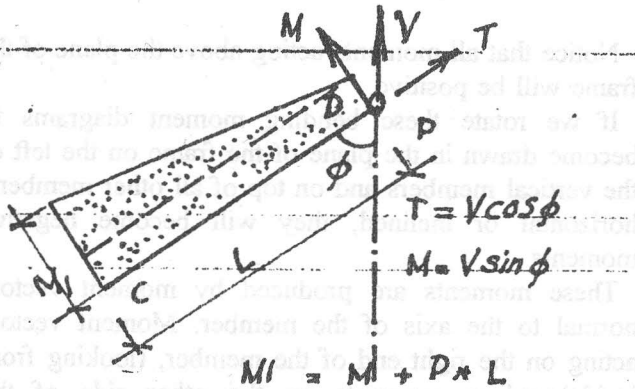


Fig. (1)

Resolution of end vectors. (A) (Member CD)

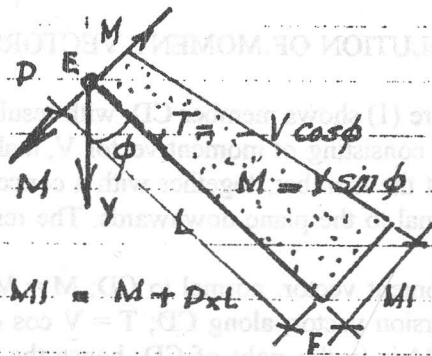


Fig. (2)

Resolution of end vectors. (B) (Member EF)

Direction of Sight

As previously given "VW"⁽¹⁾, we shall look to vertical members from left, and to other members upwards.

EXAMPLES

Example (1)

The data for example (1) is shown in program "DATVWN 4M". In this data program we see the following remarks.

In 3010, notice that the value of N equals $4 * n_0$ of members = $4 * 4 = 16$

In 3030 the n_0 of elastic lengths = $2 * n_0$ of member = $2 * 4 = 8$. For each member we give two elastic lengths, the second of which corresponds to the member resisting torsion for which $L1 = L1 * T1$.

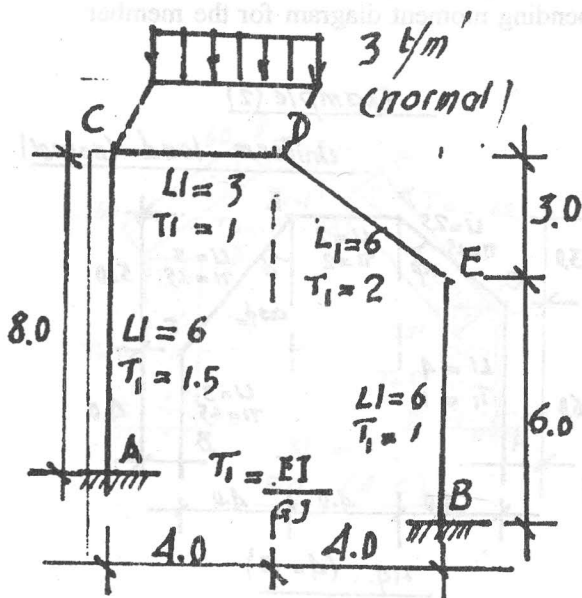
In 3040, we see the values of the moments, then the torsion in each members due to the given loads on the statically determinate frame obtained by producing a cut section in the second member in the frame. [Figure (3b)].

In this diagram the bending moments are drawn as shown. Posite moments are drawn to the right of vertical members, and on bottom of all other member.

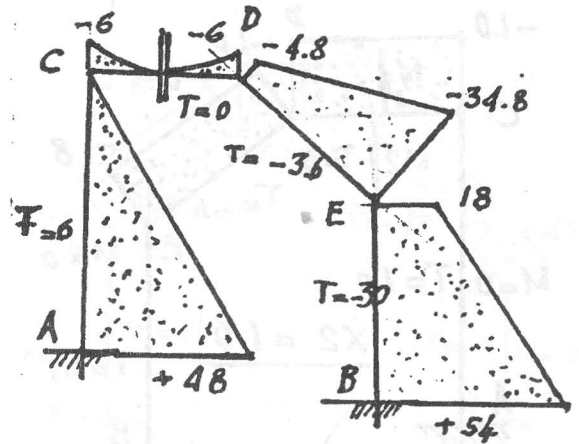
In 3080 we show the additional average ordinates of the bending moments. $A = pL^2/12$ for uniform loads. These values appear only in bending moments, while the values are zero for torsions. For this example, $A = 3 * 16/12 = 4$ in member O.

Lines 3250, 3270 refer only to the cases of settlements of supports and temperature changes or ties and hence will be zero in this example, the member equals to the R value for each line.

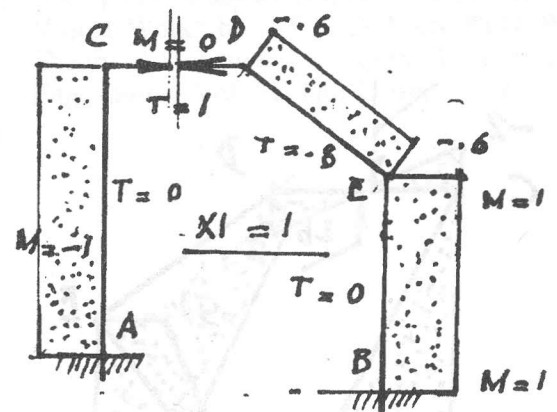
Example (1)



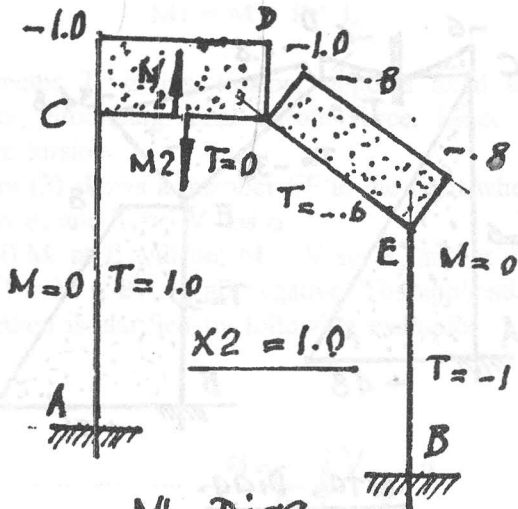
Ind. Frame
Fig. (3.a)



MTO. Diag.
Fig. (3.b)



MI. Diag.
Fig. (3.c)



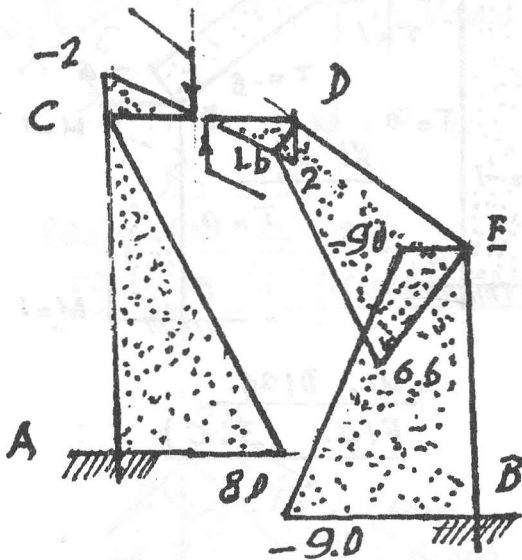
Mi. Diag.
Fig. (3. d)

Example (2)

This is shown in Figures (4a,b,c,d and e). Figures (1) and (2) will be useful when computing the MTO diagrams.

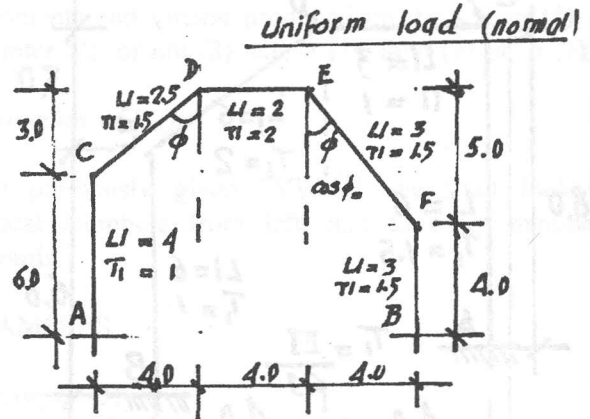
We remember the following remarks:

1. The uniform load normal to each member must be considered when evaluating the M_{T0} values at the corners. On any member the uniform load will give a concentrated load at the mid-point equal to pL , and hence an end moment equal to $pL^2/2$.
2. On each member there will be an additional average value equal to $pL^2/12$ with opposite sign to the bending moment diagram for the member



x3. Diag.
Mi. Diag.
Fig. (3. e)

Example (2)



Uniform load (normal)
fig. (4-a)
Ind. Frame
 $p = -1 \text{ t/m'}$


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10 PRINT TAB(4), " NAME OF PROGRAM ---- VWWN ---- " : PRINT
20 PRINT TAB(4), " THIS PROGRAM GIVES THE SOLUTION BY VW " : PRINT
25 PRINT TAB(4) "TO INDETERMINATE FRAMES LOADED BY LOADS NORMAL TO " : PRINT
27 PRINT TAB(6) "          THEIR PLANES          " : PRINT
30 PRINT "-----" : PRINT : PRINT
40 REM R = NOM. OF REDUNDANT VALUES
50 REM N = NOM. OF MOMENTS AND TORSION AT THE ENDS OF MEMBERS
60 REM MTO = MOMENTS (MOMENTS OR TORSIONS ) IN THE M.S DUE TO GIVEN LOADS
70 REM M(I) = MOMENTS AND TORSIONS DUE TO X(I) = 1
90 REM G GIVES THE POSITION OF THE C.G. OF ADDITIONAL MO DIAG.
100 REM A = AVERAGE MOMENT IN THE ADDITIONAL MTO DIAG.
110 REM D(I) = DISPLACEMENT COEFS. FROM MTO & M(I) DIAGS.
120 REM S(I,J) = ..... FROM APPROPRIATE M(I,J) DIAGS.
140 REM T(I) = ADDITIONAL VALUE TO S(I,J) DUE TO TIE IF ANY
150 REM U(I) = ..... D(I) DUE TO SETTLEMENT IF ANY
180 READ R , N
190 PRINT " R = " , R : PRINT " N = " , N : PRINT
210 DIM L1(N/2) , MTO(N) , A(N/2) , G(N/2) , Z(R , 2 * R)
220 DIM D(R) , M(R,N) , S(R,R) , C(R,R) , MT(N)
240 PRINT TAB(4) " 1 - ELASTIC LENGTHES L1(I) " : PRINT
250 FOR I = 1 TO (N / 2)
260 READ L1(I) : PRINT L1(I), : NEXT I : PRINT
280 PRINT TAB(4) " 2 - MOMENTS MTO IN M.S. " : PRINT
290 FOR I = 1 TO N
300 READ MTO(I) : PRINT MTO(I), : NEXT I : PRINT
320 PRINT TAB(4) " 3 - AVERAGE ADDITIONAL AREAS A(I) IN MTO DIAG." : PRINT
330 FOR I = 1 TO N / 2
340 READ A(I) : PRINT A(I), : NEXT I : PRINT
360 PRINT TAB(4) " 4 - POSITION OF CENTROID G FOR CG. OF A " : PRINT
370 FOR I = 1 TO N / 2
380 READ G(I) : PRINT G(I), : NEXT I : PRINT
400 PRINT TAB(4) " 5 - MOMENTS M(I,J) DUE TO M(I) = 1 " : PRINT
410 FOR I = 1 TO R
420 FOR J = 1 TO N
430 READ M(I,J) : PRINT M(I,J) , : NEXT J
440 PRINT : NEXT I : PRINT
460 PRINT TAB(4) " 6 - ADDITIONAL DISP. COEF. U(I) DUE TO SETTLEMENT " : PRINT
470 FOR I = 1 TO R
480 READ U(I) : PRINT U(I), : NEXT I : PRINT
500 PRINT TAB(4) " 7 - ADDITIONAL DISP. COEF. T(I) DUE TO TIES " : PRINT
510 FOR I = 1 TO R
520 READ T(I) : PRINT T(I), : NEXT I : PRINT
550 PRINT TAB(6) " 8 - DISP. COEFS. D(I) DUE TO MTO , M DIAG." : PRINT
560 FOR I = 1 TO R
570 D(I) = 0
580 FOR K = 1 TO (N - 1) STEP 2
590 D(I) = D(I) + L1((K+1)/2) * ( MTO(K)*M(I,K) /3 + MTO(K+1) * M(I, (K+1)) /
)
600 D(I) = D(I) + L1((K+1)/2) * (MTO(K)* M(I, (K+1)) /6 + MTO(K+1)* M(I, K) /6)

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610 D(I) = D(I) + L1((K+1)/2) * A((K+1)/2) * M(I, (K+1)) * G((K+1)/2)
620 D(I) = D(I) + L1((K+1)/2) * A((K+1)/2) * (1-G((K+1)/2)) * M(I, K)
640 NEXT K
650 D(I) = D(I) + U(I)
660 PRINT D(I) : NEXT I : PRINT
700 PRINT TAB(4) "9 - DISP. COEFS. S(I, J) DUE TO M(I, J) " : PRINT
710 FOR I = 1 TO R
720 FOR J = 1 TO R
730 S(I, J) = 0
740 FOR K = 1 TO (N-1) STEP 2
750 S(I, J) = S(I, J) + L1((K+1)/2) * (M(I, K)*M(J, K)/3 + M(I, (K+1))*M(J, (K+1))/3)
760 S(I, J) = S(I, J) + L1((K+1)/2) * (M(I, K)*M(J, (K+1))/6 + M(I, (K+1))*M(J, K)/6)
770 NEXT K
780 IF J <> I THEN GOTO 800
790 S(I, J) = S(I, J) + T(I)
800 NEXT J : NEXT I
820 FOR I = 1 TO R
830 FOR J = 1 TO R
840 PRINT S(I, J), : NEXT J : PRINT
850 NEXT I : PRINT
880 PRINT TAB(4) " 10 - FLEXIBILITY MATRIX V = INVERS OF S " : PRINT
910 FOR I = 1 TO R
920 FOR J = 1 TO R
930 Z(I, J) = S(I, J)
940 NEXT J : NEXT I : PRINT
950 IF R = 1 THEN V(1, 1) = 1 / S(1, 1) : PRINT V(1, 1) : GOTO 1000
980 GOSUB 10000
1000 PRINT TAB(4) " 11 - REDUNDANT VALUES X (R) " : PRINT
1110 FOR I = 1 TO R
1120 X(I) = 0
1140 FOR K = 1 TO R
1150 X(I) = X(I) - V(I, K) * D(K)
1160 NEXT K : NEXT I
1170 FOR I = 1 TO R
1180 PRINT X(I) : NEXT I : PRINT
1200 PRINT TAB(4) " 12 - FINAL B.MOMENTS MT(I) " : PRINT
1210 FOR I = 1 TO N
1220 MT(I) = 0
1230 FOR J = 1 TO R
1240 MT(I) = MT(I) + X(J) * M(J, I)
1250 NEXT J
1260 MT(I) = MT(I) + MTO(I)
1270 NEXT I
1272 INPUT "YOU WANT SCREEN (1) OR PRINTER (2) , OR END (3) " , SP
1274 ON SP GOTO 1280 , 1360 , 1500
1280 FOR I = 1 TO (N-1) STEP 2
1290 PRINT MT(I) , MT(I+1)
1310 NEXT I : PRINT
1320 PRINT TAB(4) " THIS IS ALL NOW " : PRINT
1340 GOTO 1272
1360 FOR I = 1 TO (N-1) STEP 2
1370 LPRINT MT(I) , MT(I+1)
1380 NEXT I : LPRINT
1400 LPRINT TAB(4) " THAT IS ALL NOW " : LPRINT
1500 END

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10000   FOR I = 1 TO R
10010     FOR J = (R+1) TO 2 * R
10020       Z(I,J) = 0
10030     NEXT J
10035     Z(I , R+I) = 1
10040     NEXT I
10050     P = 0
10060     P = P + 1
10070     C(P,P) = Z(P,P)
10080     FOR J = 1 TO (2 * R)
10090       Z(P,J) = Z(P,J) / C(P,P)
10100     NEXT J
10110     FOR I = (P + 1) TO R
10120       C(I,P) = Z(I,P)
10130     FOR J = P TO 2 * R
10140       Z(I,J) = Z(I,J) - C(I,P) * Z(P,J)
10150     NEXT J
10160     NEXT I
10170     IF P = 1 THEN 10060
10180     FOR I = 1 TO (P-1)
10190       C(I,P) = Z(I,P)
10200     FOR J = P TO (2 * R)
10210       Z(I,J) = Z(I,J) - C(I,P) * Z(P,J)
10220     NEXT J
10230     NEXT I
10240     IF P = R THEN GOTO 10260
10250     GOTO 10060
10260     FOR I = 1 TO R
10270       FOR J = 1 TO R
10280         V(I,J) = Z(I,R+J)
10290     PRINT V(I,J) , : NEXT J
10300     PRINT : NEXT I : PRINT
10320     RETURN

```

DATVWN M

```

3000 PRINT " ENTER DATA FOR R , N "
3020 PRINT " ENTER DATA FOR ELASTIC LENGTHES L(I) "
3040 PRINT " ENTER DATA B.MOMENTS AND TOESION MT0(I) IN M.S. "
3080 PRINT " ENTER DATA FOR ADDITIONAL AVERAGE ORDINATE IN A(I) "
3120 PRINT " ENTER DATA FOR G: CENTROID OF ADDIT. AREA A(I) "
3160 PRINT " ENTER DATA FOR M(I,J) DUE TO M(I) = 1 "
3240 PRINT " ENTER DATA FOR ADDITIONAL DISP. COEFS. U(I) "
3260 PRINT " ENTER DATA FOR ADDITIONAL DISP. COEFS. T(I) "

```


Example (1) "DATVWN4M"

```

3000 PRINT " ENTER DATA FOR R , N "
3010 DATA 3 , 16
3020 PRINT " ENTER DATA FOR ELASTIC LENGTHES L(I) "
3030 DATA 6,9, 3,3, 6,12, 6,6
3040 PRINT " ENTER DATA B.MOMENTS AND TORSIONS MT0(I) IN M.S. "
3050 DATA 48,0, 6,6, -6,-6, 0,0, -4.8,-34.8, -3.6,-3.6
3060 DATA 18,54, -30,-30
3080 PRINT " ENTER DATA FOR ADDITIONAL AVERAGE ORDINATE IN A(I) "
3090 DATA 0,0, 4,0, 0,0, 0,0
3120 PRINT " ENTER DATA FOR G: CENTROID OF ADDIT. AREA A(I) "
3125 DATA 0.5,0.5, 0.5,0.5, 0.5,0.5, 0.5,0.5
3160 PRINT " ENTER DATA FOR M(I,J) DUE TO M(I) = 1 "
3170 DATA -1,-1, 0,0, 0,0, 1, 1, -.6,-.6, .8,.8, 1,1, 0,0
3180 DATA 0,0, 1,1, -1,-1, 0,0, -.8,-.8, -.6,-.6, 0,0, -1,-1
3190 DATA 8,0, 2,2, -2,2, 0,0, 1.6,6.6, 1.2,1.2, -3,-9, 6,6
3240 PRINT " ENTER DATA FOR ADDITIONAL DISP. COEFS. U(I) "
3250 DATA 0 , 0 , 0
3260 PRINT " ENTER DATA FOR ADDITIONAL DISP. COEFS. T(I) "
3270 DATA 0 , 0 , 0
    
```

MERGE [VWNM]

R U N

66.85296	-.7879229
1.545921	1.545921
-1.545921	8.274521
.7879229	.7879229
6.146863	-11.57759
5.595051	5.595051
11.42259	32.69193
-5.905039	-5.905039

THAT IS ALL NOW

Example (2) "DATVWN6M"

```

3000 PRINT " ENTER DATA FOR R , N "
3010 DATA 3 , 20
3020 PRINT " ENTER DATA FOR ELASTIC LENGTHES L1(I) "
3030 DATA 4 , 4 , 2.5 , 3.75 , 2 , 4 , 3 , 4.5 , 3 , 4.5
3040 PRINT " ENTER DATA B.MOMENTS MTO(I) IN M.S. "
3050 DATA 73.5 , 13.5 , 20 , 20 , -24.1 , -1.6 , 1.2 , 1.2 , -2 , -2
3055 DATA 0 , 0 , -1.245 , -34.555 , -1.562 , -1.562
3057 DATA 26.008 , 67.62 , -22.806 , -22.806
3080 PRINT " ENTER DATA FOR ADDITIONAL AVERAGE ORDINATE IN A(I) "
3090 DATA -3 , 0 , 2.083 , 0 , 1.33 , 0 , 3.417 , 0 , -1.33 , 0
3120 PRINT " ENTER DATA FOR G: CENTROID OF ADDIT. AREA A(I) "
3125 DATA .5 , .5 , .5 , .5 , .5 , .5 , .5 , 5 , .5 , .5
3160 PRINT " ENTER DATA FOR M(I,J) DUE TO M(I) = 1 "
3170 DATA 1 , 1 , 0,0 , -.6,-.6 , -.8,-.8 , 0,0 , -1,-1 , .781,.781
3172 DATA -.625,-.625 , -1,-1 , 0,0
3180 DATA 0,0 , 1,1 , -.8,-.8 , .6,.6 , -1,-1 , 0,0
3182 DATA -.625 , -.625 , -.781,-.781 , 0,0 , -1,-1
3190 DATA 9 , 3 , 6,6 , -6.6,-1.6 , 1.2,1.2 , -2,2 , 0,0
3192 DATA 1.249,7.652 , 1.56,1.56 , -5,-9 , 6,6
3240 PRINT " ENTER DATA FOR ADDITIONAL DISP. COEFS. U(I) "
3250 DATA 0 , 0 , 0
3260 PRINT " ENTER DATA FOR ADDITIONAL DISP. COEFS. T(I) "
3270 DATA 0 , 0 , 0
    
```

MERGE [VWNM]

R U N

```

66.85296      -.7879229
1.545921      1.545921
-1.545921     8.274521
.7879229      .7879229
6.146863     -11.57759
5.595051      5.595051
11.42259     32.69193
-5.905039    -5.905039
    
```

THAT IS ALL NOW